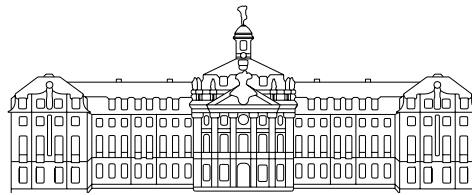

Numerical solution of the Schrödinger equation on unbounded domains

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Cetraro, September 2006

OUTLINE

→ Transparent boundary conditions (TBC)

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- Extension of the DTBC to (nearly) arbitrary potentials

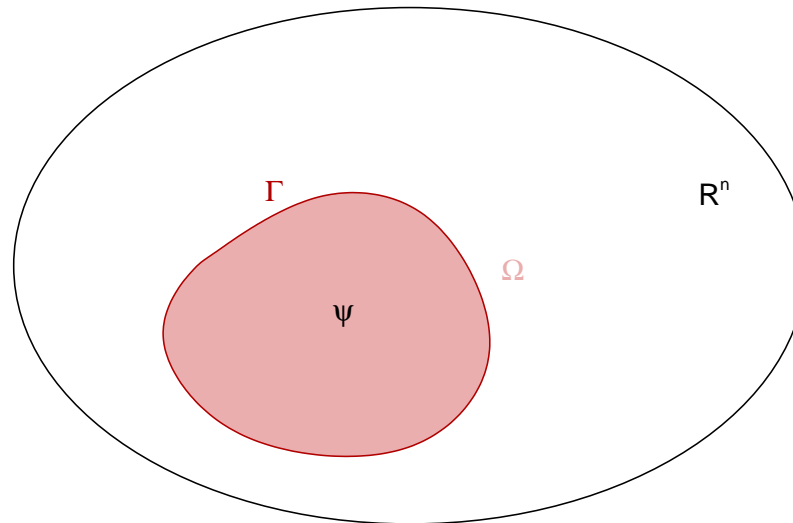
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- Extension of the DTBC to (nearly) arbitrary potentials
- more realistic simulations
- solving the Schrödinger equation on circular domains

TRANSPARENT BOUNDARY CONDITIONS (IN GENERAL)



Definition (TBC):

Consider a given whole-space initial value problem (IVP) on \mathbb{R}^n and $\Omega \subset \mathbb{R}^n$, $\Gamma = \partial\Omega$. We are interested in the solution of the IVP on Ω . Therefore we need new artificial boundary conditions on Γ . We call these artificial BC transparent, if the solution of the IVBP on Ω corresponds to the whole-space solution of the IVP restricted on Ω .

ANALYTICAL TBC FOR THE SCHRÖDINGER EQUATION

IVP: time-dependent Schrödinger equation (here: 1D)

$$\begin{aligned}i\hbar \frac{\partial}{\partial t} \psi(x, t) &= \left(-\frac{\hbar^2}{2m^*} \frac{\partial^2}{\partial x^2} + V(x, t) \right) \psi(x, t), & x \in \mathbb{R}, t > 0 \\ \psi(x, 0) &= \psi^I(x) \in L^2(\mathbb{R})\end{aligned}$$

on a domain of interest $\Omega = \{x \in \mathbb{R} | 0 < x < X\}$.

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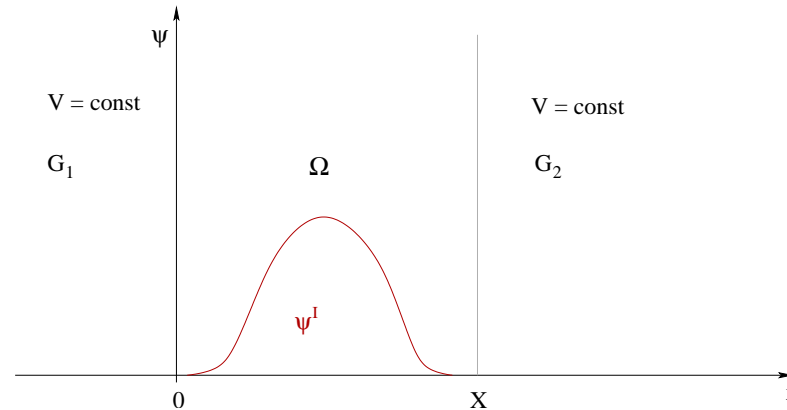
Assumptions:

- $\text{supp } \psi^I \subseteq \Omega$
- potential $V(\cdot, t) \in L^\infty(\mathbb{R})$, $V(x, \cdot)$ is piecewise continuous
- V constant on $\mathbb{R} \setminus \Omega$ (here: $V(x, t) = 0$ for $x \leq 0$ and $V(x, t) = V_X$ for $x \geq X$)

Goal:

Calculate the solution $\psi(x, t) \in \mathbb{C}$ on Ω with TBC at $x = 0$ and $x = X$.

DERIVATION OF TBC



$x \in G_1 :$

$$i\hbar\psi_t = -\frac{\hbar^2}{2m^*}\psi_{xx} + V(x,t)\psi$$

$$\psi(x, 0) = \psi^I(x)$$

$$\psi_x(0, t) = (T_0\psi)(0, t)$$

$$\psi_x(X, t) = (T_X\psi)(X, t)$$

$x \in G_2 :$

$$i\hbar\psi_t = -\frac{\hbar^2}{2m^*}\psi_{xx} + V(x,t)\psi$$

$$v(x, 0) = 0$$

$$v(X, t) = \Phi(t) \quad t > 0, \quad \Phi(0) = 0$$

$$\lim_{x \rightarrow \infty} v(x, t) = 0$$

$$v_x(0, t) = (T_X\Phi)(t)$$

Laplace-transformation on the exterior domains:

$$\hat{v}_{xx}(x, s) + \frac{2im^*}{\hbar} \left(s + \frac{iV_X}{\hbar} \right) \hat{v}(x, s) = 0 \quad x > X$$

$$\hat{v}(X, s) = \hat{\Phi}(s)$$

$$\lim_{x \rightarrow \infty} \hat{v}(x, s) = 0$$

$$\hat{v}_x(X, s) = \widehat{(T_X \Phi)}(s)$$

solution:

$$\hat{v}(x, s) = e^{-i \sqrt{\frac{2im^*}{\hbar} \left(s + \frac{iV_X}{\hbar} \right)} (x-X)} \hat{\Phi}(s)$$

$$\Rightarrow \widehat{(T_X \Phi)}(s) = -\sqrt{\frac{2m^*}{\hbar}} e^{-\frac{i\pi}{4}} \sqrt{s + \frac{iV_X}{\hbar}} \hat{\Phi}(s)$$

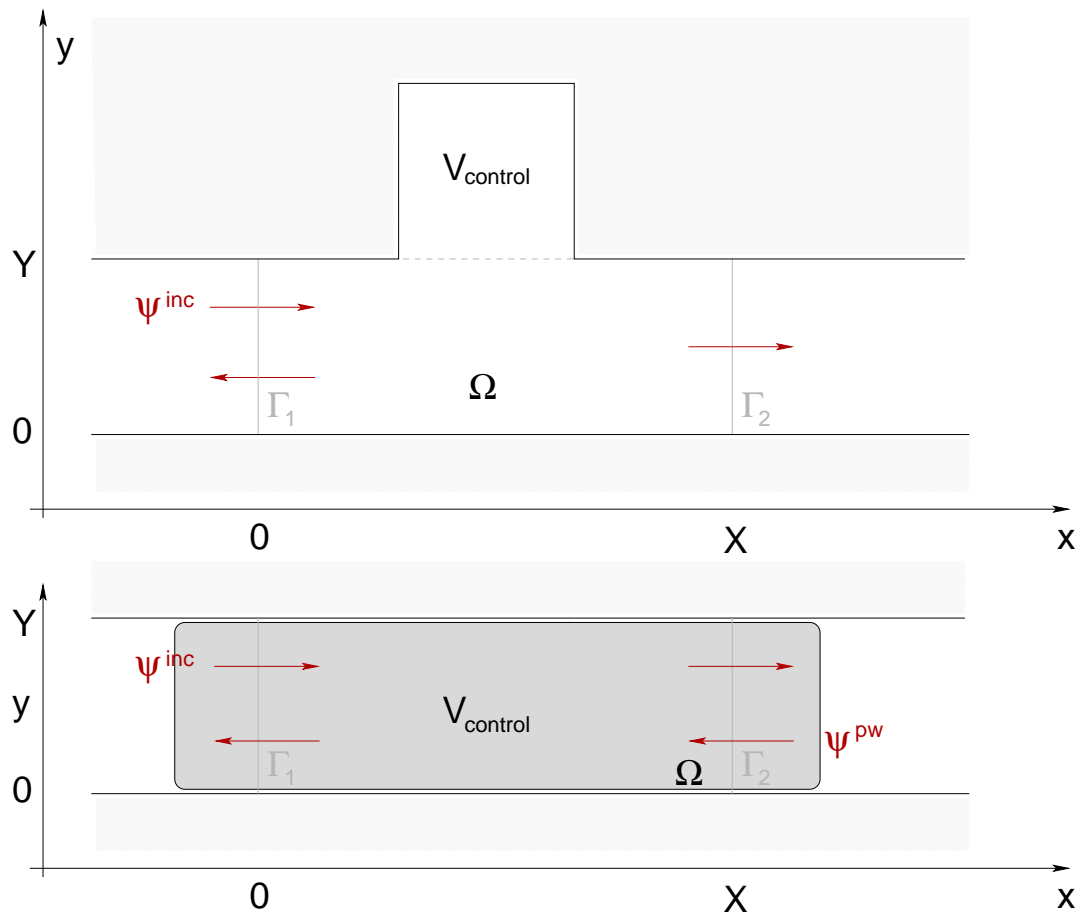
With the inverse Laplace-Transformation follows the analytical TBC

$$\psi_x(X, t) = -\sqrt{\frac{\hbar}{2\pi m^*}} e^{-i\frac{\pi}{4}} e^{-i\frac{V_X}{\hbar}t} \frac{d}{dt} \int_0^t \frac{\psi(X, \tau) e^{i\frac{V_X \tau}{\hbar}}}{\sqrt{\tau - t}} d\tau.$$

[J. S. Papadakis (1982)]

Application of DTBC for the Schrödinger equation:

- Simulation of quantum transistors in quantum waveguides (with inhomogeneous DTBC for the 2D Schrödinger equation)
- Analyse steady states and transient behaviour



FORMER STRATEGIES:

- Discretization of the analytic TBCs with an numerical approximation of the convolution integral [e.g. B. Mayfield (1989)]

⇒ only conditionally stable, not transparent!

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- Create a buffer zone Θ of the length d with a complex potential $V(X) = W - iA$ around the computational domain Ω with Dirichlet 0-BC at $\partial\Theta$ and *absorbing boundary conditions* on $\partial\Omega$ [e.g. L. Burgnies (1997)]



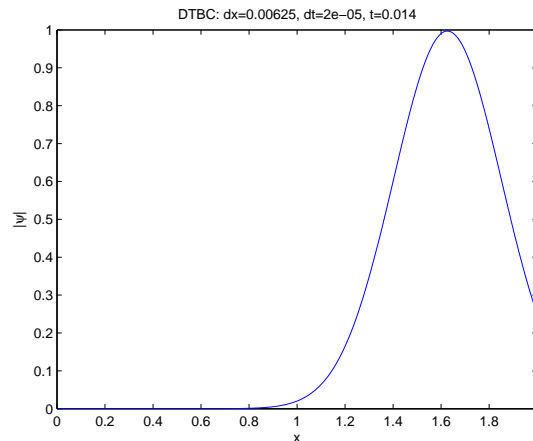
⇒ unconditionally stable, unphysical reflections at the boundary, huge numerical costs

SUCCESSFUL STRATEGIES

- Family of absorbing BCs (also for the non-linear Schrödinger equation, wave equation)

[J. Szeftel (2005)]

- discretize the whole space problem with an unconditionally stable scheme (e.g. Crank-Nicolson finite difference scheme) and calculate new **discrete transparent boundary conditions** for the full discretized Schrödinger equation



[A. Arnold, M. Ehrhardt (since 1995)]

DERIVATION OF DISCRETE TRB

Discretize 2D Schrödinger equation:

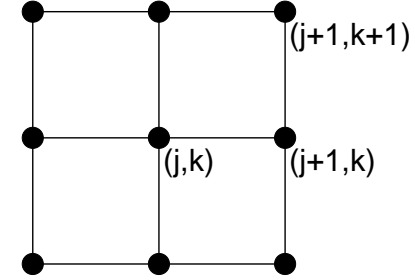
- Crank-Nicolson scheme in time, $t_n = n\Delta t$, $n \in \mathbb{N}$, $H := -\frac{1}{2}\Delta + V$
Hamilton-Operator, $\Omega = [0, X] \times [0, Y]$

$$\left(1 + \frac{iH\Delta t}{2}\right) \psi(x, y, t + \Delta t) = \left(1 - \frac{iH\Delta t}{2}\right) \psi(x, y, t)$$

$$\begin{aligned} \Rightarrow \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) (\psi^{n+1}(x, y) + \psi^n(x, y)) \\ = g^{n+\frac{1}{2}}(x, y) (\psi^{n+1}(x, y) + \psi^n(x, y)) + W\psi^n(x, y) \end{aligned}$$

- compact 9-point scheme in space, $x_j = j\Delta x$, $y_k = k\Delta y$ with
 $j \in \mathbb{Z}$, $0 \leq k \leq K$
- DTBC at $x_0 = 0$ and $x_J = X = J\Delta x$ with $J \in \mathbb{Z}$
- 0-BC at $y = 0$ and $y = Y = K\Delta y$ with $K \in \mathbb{N}$

9-point discretization scheme:



$$\begin{aligned} & \left(D_x^2 + D_y^2 + \frac{\Delta x^2 + \Delta y^2}{12} D_x^2 D_y^2 \right) \psi_{j,k}^{n+\frac{1}{2}} \\ &= \left(I + \frac{\Delta x^2}{12} D_x^2 + \frac{\Delta y^2}{12} D_y^2 \right) \left[2V_{j,k}^{n+\frac{1}{2}} \psi_{j,k}^{n+\frac{1}{2}} - 2iD_t^+ \psi_{j,k}^n \right] \end{aligned}$$

with

$$\begin{aligned} \psi_{j,k}^{n+\frac{1}{2}} &= \frac{1}{2} (\psi_{j,k}^{n+1} + \psi_{j,k}^n) \\ D_t^+ \psi_{j,k}^n &= \frac{\psi_{j,k}^{n+1} - \psi_{j,k}^n}{\Delta t}, \quad n \geq 0 \\ D_x^2 \psi_{j,k}^n &= \frac{\psi_{j-1,k}^n - 2\psi_{j,k}^n + \psi_{j+1,k}^n}{\Delta x^2}, \quad j \in \mathbb{Z} \\ D_y^2 \psi_{j,k}^n &= \frac{\psi_{j,k-1}^n - 2\psi_{j,k}^n + \psi_{j,k+1}^n}{\Delta y^2}, \quad k \in \mathbb{N} \end{aligned}$$

Discrete Sine-Transformation in y-direction:

$$\hat{\psi}_{j,m}^n := \frac{1}{K} \sum_{k=1}^{K-1} \psi_{j,k}^n \sin\left(\frac{\pi km}{K}\right) \quad m = 0, \dots, K$$

Motivation:

Solve discrete stationary Schrödinger equation in 1D:

$$-\frac{1}{2} \Delta_y^2 \chi_{j,k}^m = E^m \chi_{j,k}^m, \quad k = 0, \dots, K$$
$$\chi_{j,0}^m = \chi_{j,K}^m = 0.$$

The eigenfunctions $\chi_{j,k}^m = \sin\left(\frac{\pi km}{K}\right)$ provide the energies

$$E^m = \frac{1}{\Delta y^2} \left(1 - \cos\left(\frac{\pi m}{K}\right)\right).$$

Hence follows for $m = 0, \dots, K$

$$\Rightarrow -\frac{1}{2\Delta y^2} \left(\psi_{j,k-1}^n - 2\psi_{j,k}^n + \psi_{j,k+1}^n\right)_m^{\wedge} = \frac{1}{\Delta y^2} \left(1 - \cos\left(\frac{\pi m}{K}\right)\right) \hat{\psi}_{j,m}^n.$$

Sine-Transformation of the discrete Schrödinger equation on the exterior domains $j \leq 0$, $j \geq J$ yields for the modes $m = 0, \dots, K$:

$$\begin{aligned} & C_{j+1}^m \hat{\psi}_{j+1,m}^{n+1} + C_{j-1}^m \hat{\psi}_{j-1,m}^{n+1} + R_j^m \hat{\psi}_{j,m}^{n+1} \\ &= (D - C_{j+1}^m) \hat{\psi}_{j+1,m}^n + (D - C_{j-1}^m) \hat{\psi}_{j-1,m}^n + (B_j^m - R_j^m) \hat{\psi}_{j,m}^n. \end{aligned}$$

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& = (D - C_{j+1}^m) \hat{\psi}_{j+1,m}^n + (D - C_{j-1}^m) \hat{\psi}_{j-1,m}^n + (B_j^m - R_j^m) \hat{\psi}_{j,m}^n.
\end{aligned}$$

Definition [\mathcal{Z} - Transformation]:

The \mathcal{Z} -Transformation of a sequence $(\psi^n)_{n \in \mathbb{N}}$ is given by

$$\mathcal{Z} \{ \psi^n \} = \Psi(z) := \sum_{n=0}^{\infty} \psi^n z^{-n} \quad z \in \mathbb{C}, |z| > 1.$$

One can show:

- $\mathcal{Z} \left(\hat{\psi}_{j,m}^{n+1} \right) = -z \hat{\psi}_{j,m}^0 + z \Psi_j^m(z)$
- $\psi_{J+1,k}^0 = \psi_{J-1,k}^0 = \psi_{J,k}^0 = 0$ for $k = 0, \dots, K$
- V_j constant for $j \leq 1, j \geq J - 1 \Rightarrow C_j^m = C^m, R_j^m = R^m, B_j^m = B^m$

$$\Rightarrow \Psi_{J+1}(z) + \left[\frac{Rz + R - B}{Cz + C - D} \right] \Psi_J(z) + \Psi_{J-1}(z) = 0.$$

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This difference equation with constant coefficients is solved by

$\Psi_j(z) = \nu^j(z)$:

$$\nu^2(z) + \left[\frac{Rz + R - B}{Cz + C - D} \right] \nu(z) + 1 = 0,$$

Physical background forces decay of the solution for $j \rightarrow \infty$

$\Rightarrow |\nu(z)| > 1$ und $\nu(z)\Psi_J(z) = \Psi_{J-1}(z) \rightarrow \mathcal{Z}$ -transformed DTBC

Theorem [DTBC for the 2D Schrödinger equation]: *Discretize the 2D Schrödinger-Equation with the compact 9-point difference scheme in space and with the Crank-Nicolson scheme in time. Then the DTBC at $x_J = J\Delta x$ and $x_0 = 0$ for $n \geq 1$ read*

$$\hat{\psi}_{1,m}^n - s_{0,m}^{(0)} \hat{\psi}_{0,m}^n = \sum_{\nu=1}^{n-1} s_{0,m}^{(n-\nu)} \hat{\psi}_{0,m}^\nu - a_1^m \hat{\psi}_{1,m}^{n-1},$$

$$\hat{\psi}_{J-1,m}^n - s_{J,m}^{(0)} \hat{\psi}_{J,m}^n = \sum_{\nu=1}^{n-1} s_{J,m}^{(n-\nu)} \hat{\psi}_{J,m}^\nu - a_{J-1}^m \hat{\psi}_{J-1,m}^{n-1}.$$

The convolution coefficients $s_{j,m}^{(n)}$ can be calculated by

$$s_{j,m}^{(n)} = \alpha_j^m \frac{(\lambda_j^m)^{-n}}{2n-1} \left[P_n(\mu_j^m) - P_{n-2}(\mu_j^m) \right]$$

with the Legendre-Polynomials P_n ($P_{-1} \equiv P_{-2} \equiv 0$).

Advantages of the new DTBC:

- no numerical reflections
- 3-point recursion for $s^{(n)}$
- these DTBC have exactly the same structure like the DTBC calculated with the 5-point scheme [A. Arnold, M. Ehrhardt]
- convergence: $\mathcal{O}(\Delta x^4 + \Delta y^4 + \Delta t^2)$
- same numerical effort like discretized analytical TRB
- $s_{j,m}^{(n)} = \mathcal{O}(n^{-3/2})$
- CN-FD scheme with DTBC is unconditionally stable, with $A := I + \frac{\Delta x^2}{12} D_x^2 + \frac{\Delta y^2}{12} D_y^2$ follows:

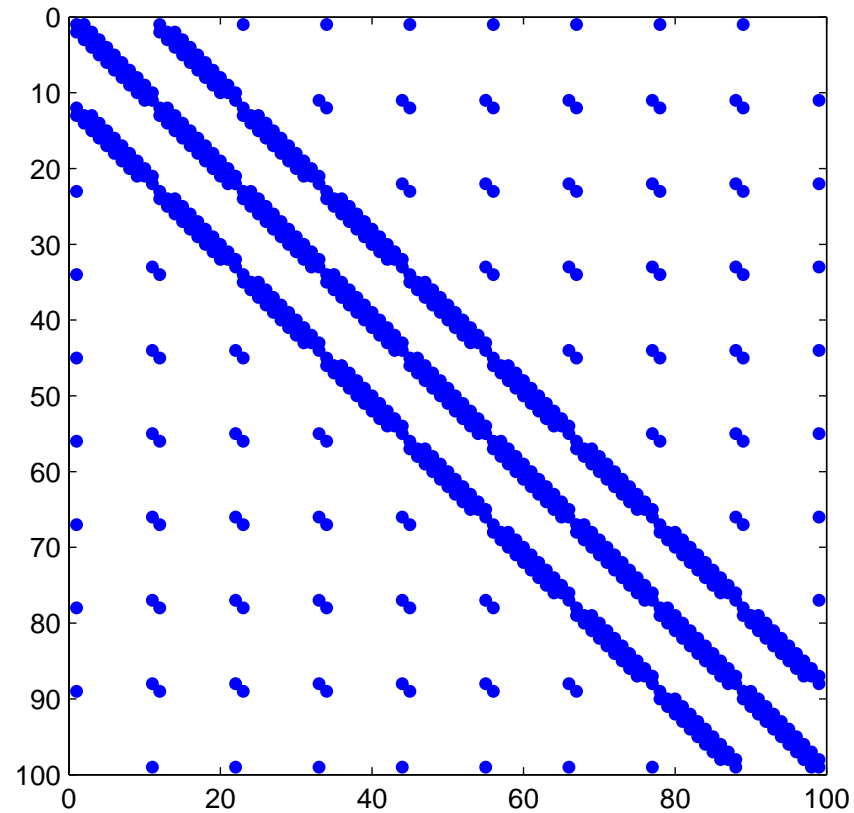
$$D_t^+ \|\psi\|_A^2 = 0 \quad \text{with} \quad \|\psi\|_A^2 := \langle \psi, A\psi \rangle. \quad (1)$$

some drawbacks:

- DTBC are non-local in time
 - high memory costs: the solution $\psi_{j,m}^n$ has to be saved in x_0 and x_J for all time steps $n = 1, 2, \dots$
 - in each time step $n = 1, 2, \dots$ you have to calculate K convolutions of the length n
(FFT not useable, $\Rightarrow \mathcal{O}(Kn^2)$)

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(FFT not useable, $\Rightarrow \mathcal{O}(Kn^2)$)
- These DTBC are given in the Sine-transformed form: BC of one mode is a linear combination of all other boundary points
 - diagonal structure of the system matrix is destroyed

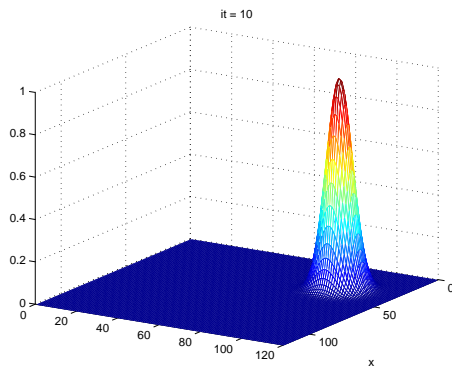


Sparsity pattern of the system matrix for $J = K = 10$

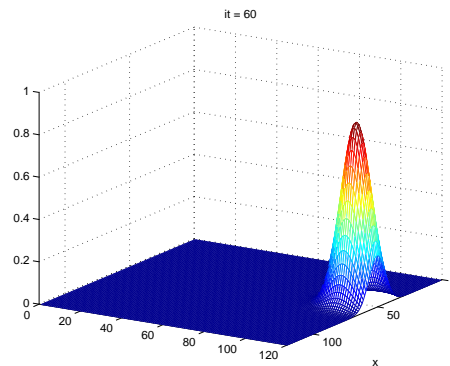
Example 1:

free 2D Schrödinger equation on $\Omega = [0, 2] \times [0, 2]$ with the initial data:

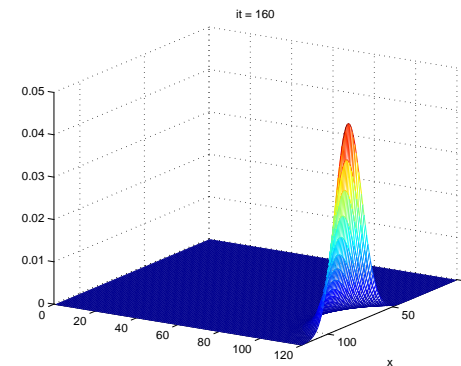
$$\psi^I(x, y) = e^{ik_x x + ik_y y - 60 \left((x - \frac{1}{2})^2 + (y - \frac{1}{2})^2 \right)}, \quad (x, y) \in \Omega$$



$$T = 10$$



$$T = 60\Delta t$$



$$T = 80\Delta t$$

APPROXIMATION OF DTBC

- Idea: Approximate the convolution coefficients $s_{j,m}^{(n)}$ by a sum of exponentials:

$$s^{(n)} \approx \tilde{s}^{(n)} = \sum_{l=1}^L b_l q_l^{-n}, \quad n \in \mathbb{N}, |q_l| > 1, L \leq 40$$

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- b_l, q_l are calculated by the Padé - Approximation of

$$f(x) = \sum_{n=0}^{2L-1} s^{(n)} x^n, \quad |x| \leq 1$$

[A.Arnold, M. Ehrhardt, I. Sofronov (2003)]

Recursion formula for the convolution coefficients:

$$\sum_{t=0}^{n-1} \tilde{s}^{(n-t)} \psi^t = \sum_{l=1}^L c_l^{(n)}$$

with

$$\begin{aligned} c_l^{(n)} &= q_l^{-1} c_l^{(n-1)} + b_l q_l^{-1} \psi^{n-1}, & n = 1, \dots, N \\ c_l^{(0)} &= 0 \end{aligned}$$

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Advantages:

→ If you have calculated b_l, q_l once for a set $\Delta x, \Delta y, \Delta t, V$, you'll easily derive b_l^*, q_l^* for any $\Delta x^*, \Delta y^*, \Delta t^*, V^*$ by

$$\begin{aligned} q_l^* &= \frac{q_l \bar{a} - \bar{b}}{a - q_l b} \\ b_l^* &= b_l q_l \frac{a \bar{a} - b \bar{b}}{(a - q_l b)(q_l \bar{a} - \bar{b})} \frac{1 + q_l^*}{1 + q_l} \end{aligned}$$

→ Numerical effort: $\mathcal{O}(Kn^2) \rightarrow \mathcal{O}(KLn)$

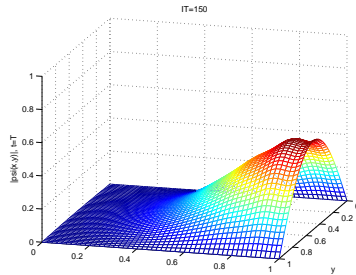
→ Memory: $\mathcal{O}(Kn) \rightarrow \mathcal{O}(KL)$

Example 2:

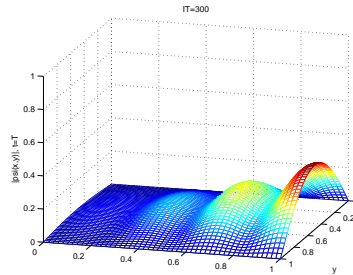
free 2D Schrödinger-Equation in $\Omega = [0, 1] \times [0, 1]$

Initial function:

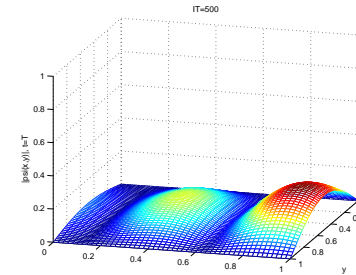
$$\psi^I(x, y) = \sin(\pi y) e^{ik_x x - 60(x - \frac{1}{2})^2}, \quad (x, y) \in \Omega$$



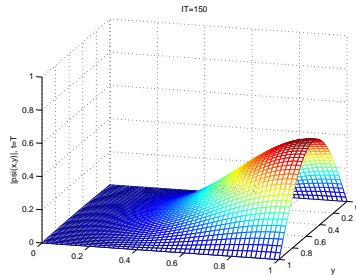
$$L = 5 : \quad T = 150\Delta t$$



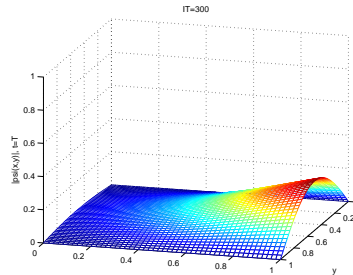
$$T = 300\Delta t$$



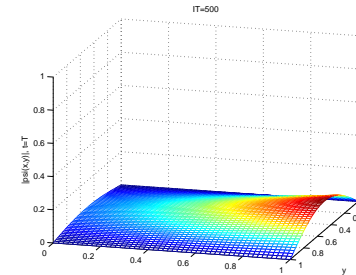
$$T = 500\Delta t$$



$$L = 20 : \quad T = 150\Delta t$$

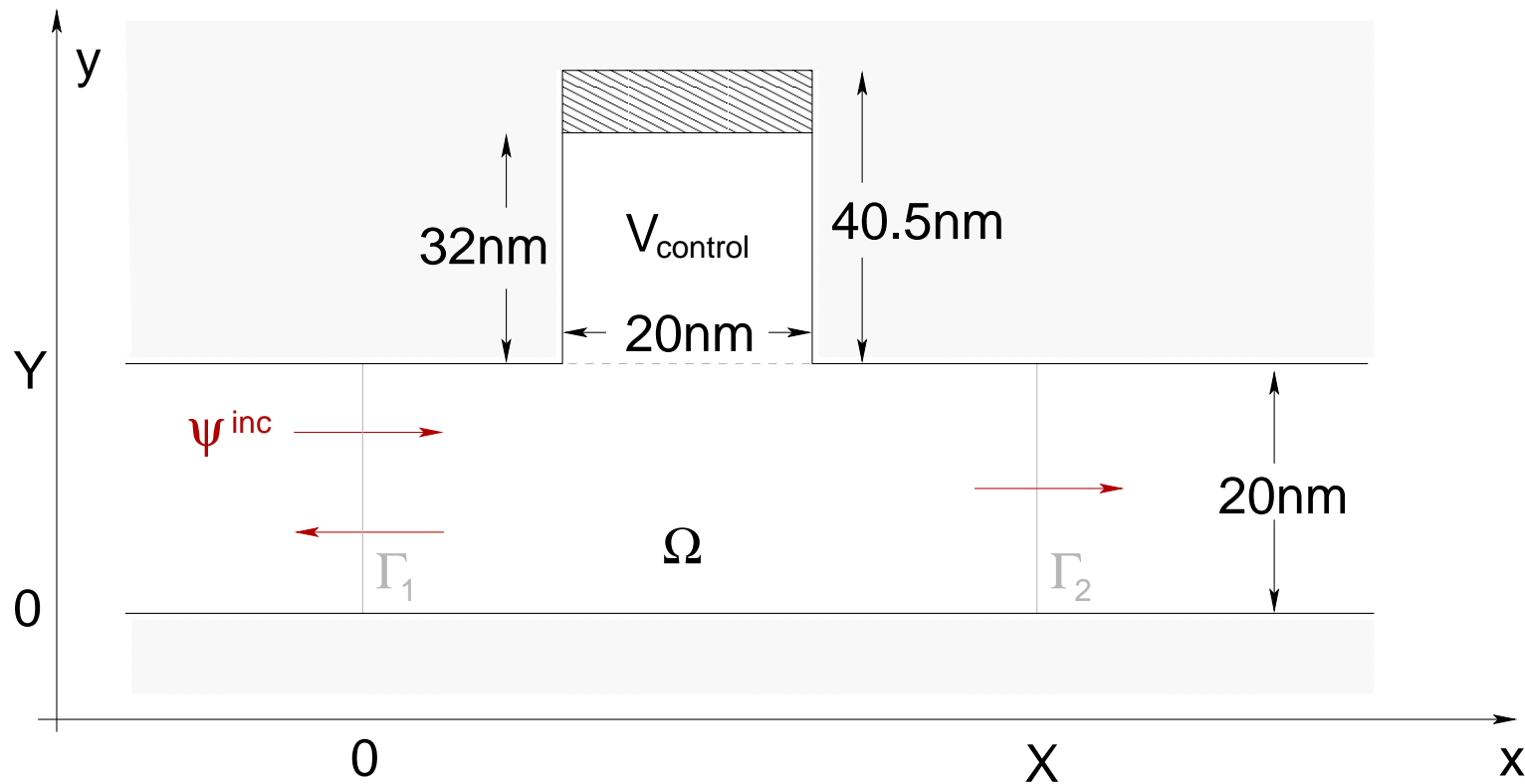


$$T = 300\Delta t$$



$$T = 500\Delta t$$

SIMULATION OF QUANTUM WAVEGUIDES



- Incoming wave at $x = 0$:

$$\psi^{\text{inc}}(0, y, t) = \sin(\pi y) e^{\frac{-iEt}{\hbar}}, \quad E = 29.9 \text{ meV}$$

- inhomogeneous DTBC at $x = 0$, DTBC at $x = X$

Little trick to suppress oscillations in time:

ψ^{inc} oscillates like $e^{\frac{-iEt}{\hbar}}$ in time.

E big:

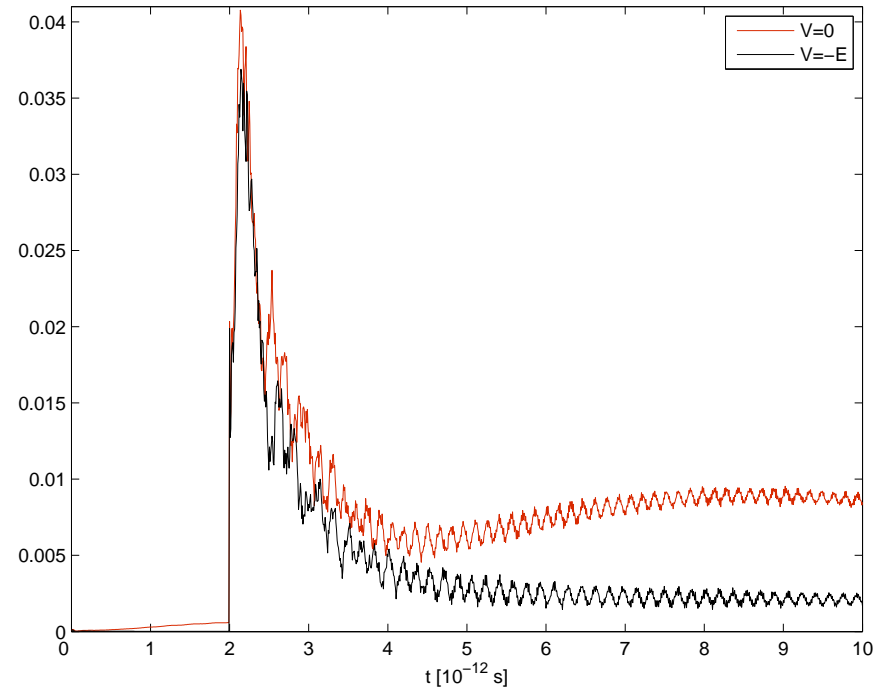
- fast oscillation of the solution in time
- small time step size is necessary
- high numerical effort for the analysis of steady state and long-time behaviour

Define

$$\varphi(x, y, t) := e^{-i\omega t} \psi(x, y, t) \quad \text{mit} \quad \omega = -\frac{E}{\hbar}.$$

φ solve the modified Schrödinger equation

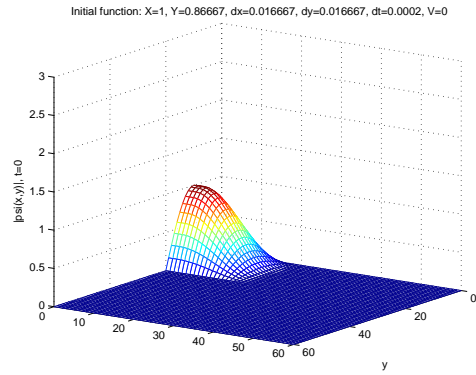
$$i\hbar\varphi_t = -\frac{\hbar^2}{2m^*}(\varphi_{xx} + \varphi_{yy}) + \underbrace{(V - \omega\hbar)}_{=:\tilde{V}}\varphi$$



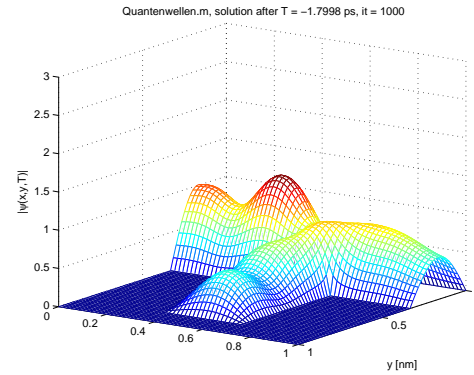
$$f_1(t) = \|\psi_1(x, y, t) - \psi_{ref}(x, y, t)\|_2$$

$$f_2(t) = \|\psi_2(x, y, t) - \psi_{ref}(x, y, t)\|_2$$

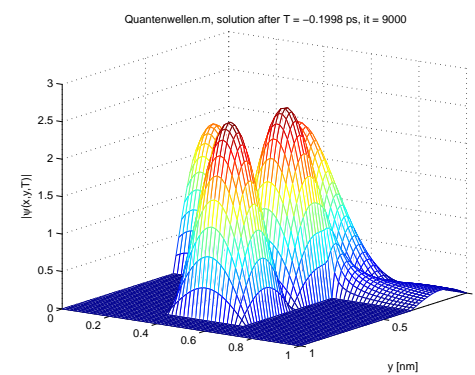
ψ_1 is calculated with $\tilde{V} = 0$, ψ_2 with $\tilde{V} = -E$ and ψ_{ref} is a numerical reference solution, which has been calculated with high accuracy.



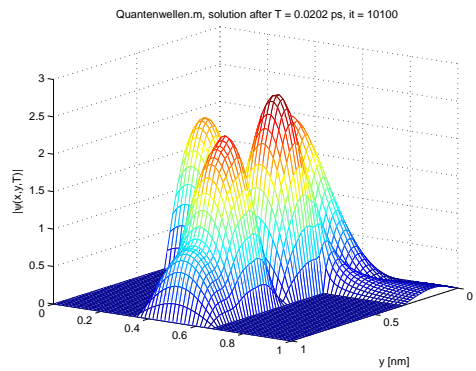
$$T = 0\Delta t$$



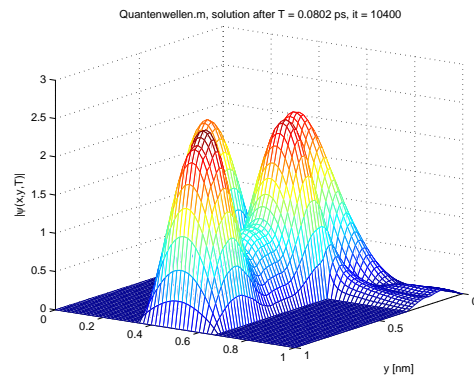
$$T = 1000\Delta t$$



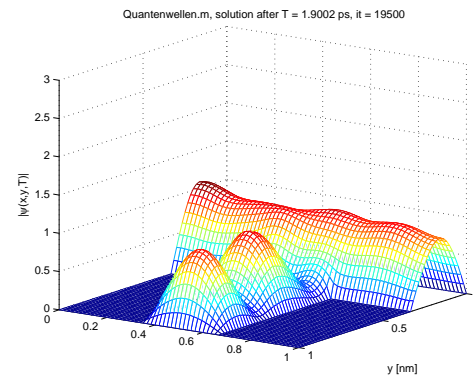
$$T = 9000\Delta t$$



$$T = 10100\Delta t$$



$$T = 10400\Delta t$$



$$T = 19500\Delta t$$

EXTENSION OF THE DTBC TO MORE ARBITRARY POTENTIALS

Drawbacks of the simulations:

- Hard walls (zero Dirichlet BCs) and edges are not practicable in industry!
 - Geometry of computational domain shall be realized by potentials also in the simulations.
 - How to choose the incoming wave and the initial function then?
- Potentials are NOT constant in the exterior domains!
 - Decoupling of the modes for $V(x, y) \neq \text{const.}$ after Sine-Transformation is not possible

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Discrete Schrödinger equation:

5-point scheme in space, Crank-Nicolson in time:

$$i\hbar D_t^+ \psi_{j,k}^n = -\frac{\hbar^2}{2m^*} (D_x^2 + D_y^2) \psi_{j,k}^{n+\frac{1}{2}} + V_{j,k}^{n+\frac{1}{2}} \psi_{j,k}^{n+\frac{1}{2}}$$

→ Calculate new Eigenfunctions, which take the potential into account!

Solve the eigenvalue equation on the exterior domains ($j \leq 0, j \geq J$):

$$-\frac{1}{2\Delta y^2} (\chi_{j,k-1,m}^n - 2\chi_{j,k,m}^n + \chi_{j,k+1,m}^n) + V_k^{n+\frac{1}{2}} \chi_{j,k,m}^n = E_{j,m}^n \chi_{j,k,m}^n$$

with

$$\Delta y \sum_{k=0}^K |\chi_{j,k,m}^n|^2 = 1 \quad \text{and} \quad \chi_{j,0,m}^n = \chi_{j,K,m}^n = 0$$

for $0 \leq k, m \leq K, n > 0$.

Transformation w.r.t. the eigenfunctions

$$\hat{\psi}_{j,m}^n = \Delta y \sum_{k=1}^{K-1} \chi_{j,k,m}^n \psi_{j,k}^n, \quad 0 \leq m \leq K.$$

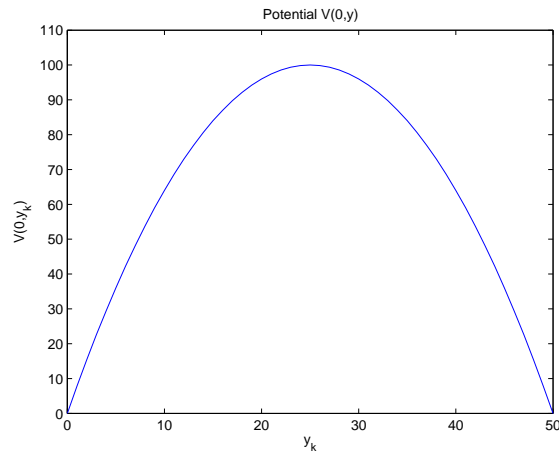
yields

$$i\hbar D_t^+ \hat{\psi}_{j,m}^n = -\frac{\hbar^2}{2m^*} D_x^2 \hat{\psi}_{j,m}^{n+\frac{1}{2}} + E_{j,m}^n \hat{\psi}_{j,m}^{n+\frac{1}{2}}$$

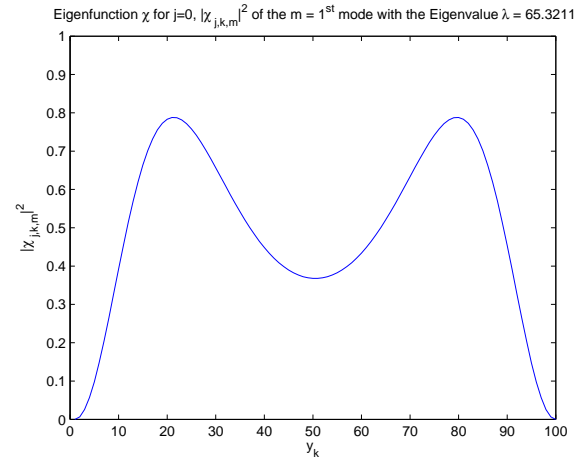
→ same structure as the sine-transformed Schrödinger equation!

[N. Ben Abdallah, M.S. (2005)]

Example 3: 2D channel



potential $V(y) = 400y(1 - y)$



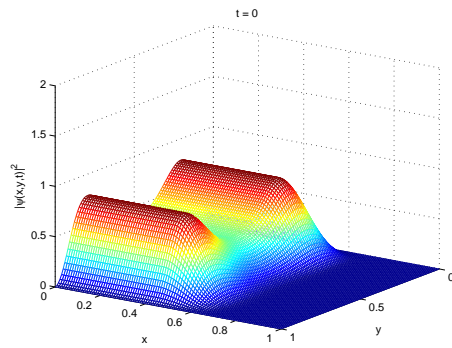
eigenfunction χ of $m = 1$

→ initial function:

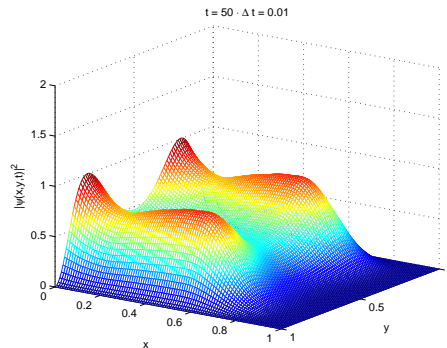
$$\psi_{j,k}^I = e^{ik_x j \Delta x} \chi_{j,k,m}^0$$

→ incoming wave:

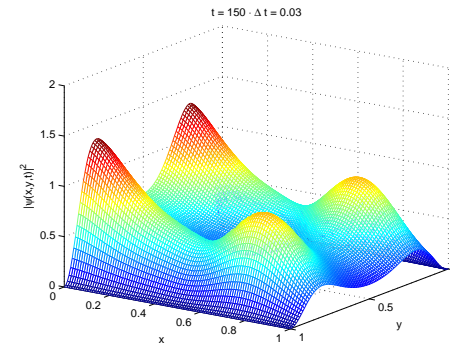
$$\psi_{j,k,n}^{inc} = e^{ik_x j \Delta x} \chi_{j,k,m}^0 e^{-iE_x n \Delta t} \quad \text{with} \quad E_x = \frac{1 - \cos(k_x \Delta x)}{\Delta x^2}$$



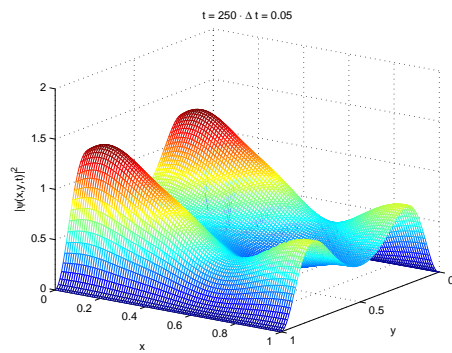
$$T = 0\Delta t$$



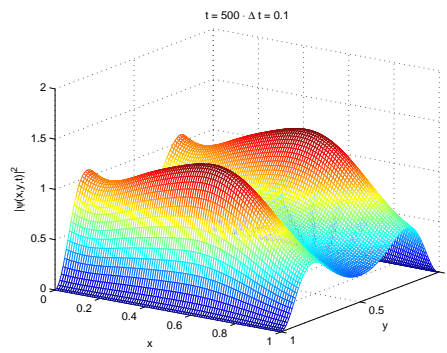
$$T = 50\Delta t$$



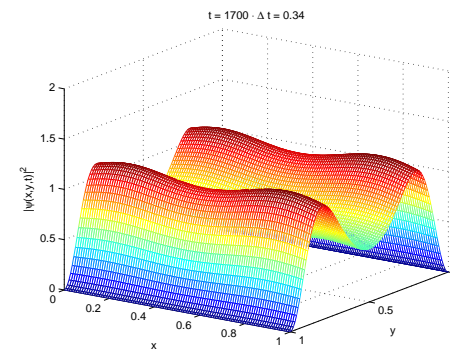
$$T = 150\Delta t$$



$$T = 250\Delta t$$



$$T = 500\Delta t$$



$$T = 1700\Delta t$$

SCHRÖDINGER EQUATION ON CIRCULAR DOMAINS

Solve the Schrödinger equation (in polar coordinates)

$$i\psi_t = -\frac{1}{2} \left(\frac{1}{r} (r\psi_r)_r + \frac{1}{r^2} \psi_{\theta\theta} \right) + V(r, \theta, t)\psi, \quad r > 0, 0 \leq \theta \leq 2\pi, t > 0$$

on a circular domain $\Omega = [0, R] \times [0, 2\pi]$ with TBC at $x = R$.

Problems:

- solve a second order difference equation with varying coefficients:

$$a_j \Psi_{J+1}(z) + b_j(z) \Psi_J(z) + c_j \Psi_{J-1}(z) = 0$$

- calculation of the convolution coefficients for the DTBC

→ "recursion from infinity"

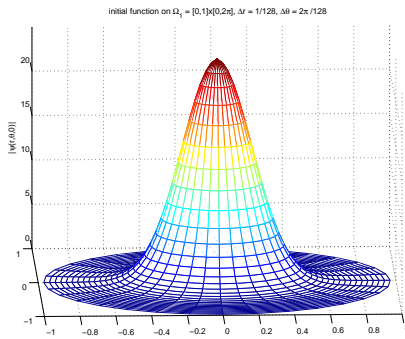
- singularity at $r = 0$ → not equidistant offset-grid $\tilde{r}_j = r_{j+\frac{1}{2}}$
- approximation of the convolution coefficients and the -sum

[A.Arnold, M. Ehrhardt, M. S., I. Sofronov (2006)]

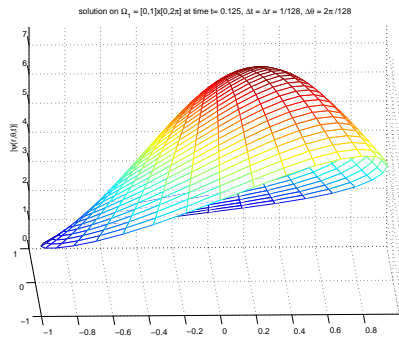
Example 4:

free Schrödinger equation on unit disc $\Omega_1 = [0, 1] \times [0, 2\pi]$

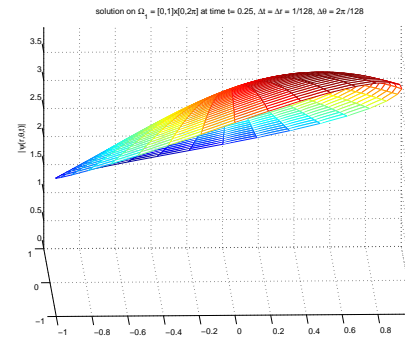
$$\psi^I(r, \theta) = \frac{1}{\sqrt{\alpha_x \alpha_y}} e^{2ik_x r \cos \theta + 2ik_y r \sin \theta - \frac{(r \cos \theta)^2}{2\alpha_x} - \frac{(r \sin \theta)^2}{2\alpha_y}}$$



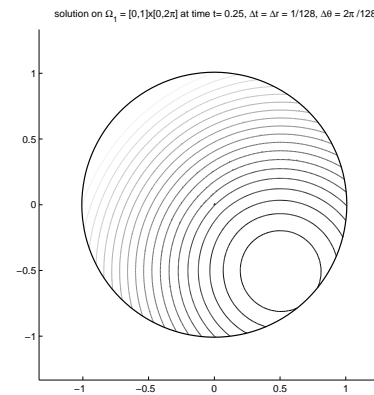
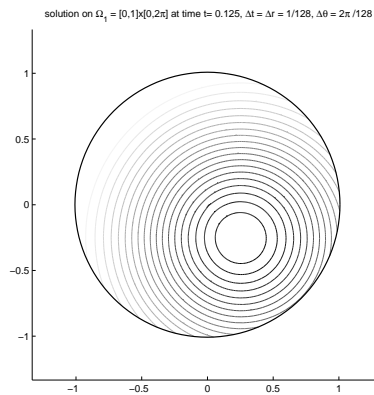
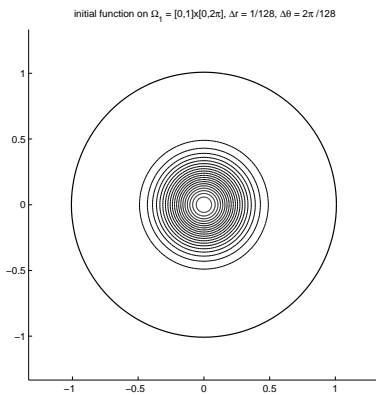
initial function



$T = 0.125$



$T = 0.25$



Error due to the scheme/TBC:

$$L(\psi, \varphi, t_n, \Omega) := \frac{\|\psi(r_j, \theta_k, t_n) - \varphi(r_j, \theta_k, t_n)\|_{\Omega, 2}}{\|\varphi(r_j, \theta_k, t_n)\|_{\Omega, 2}}$$

ψ : numerical solution

φ : exact solution or numerical reference solution

